

Robust AMD Stage Grading with Exclusively OCTA Modality Leveraging 3D Volume

Haochen Zhang, Anna Heinke, Carlo Galang, Daniel Deussen, Bo Wen, Dirk-Uwe Bartsch, William Freeman, Truong Nguyen, Cheolhong An

Computer Vision for Automated Medical Diagnosis

ICCV 2023 Workshop

Background Target AMD stages: Normal Dry: early stage Remission: after treatment Active: wet stage Fundus with given y [/] 3D OCT volume_ Select OCTA sl SVC Sum in z axis SVC projection DVC projectio Enhance quality DVC Concatenate OCTA all scans Slab mask Take one scan Avascular with given projection Avascular projection CC projection OCTA projections Example B-scan of each 3D volume 3D OCTA volume **Left:** Comparison between fundus and OCTA w.r.t. AMD stages. All AMD stages exhibit drusens in fudus while OCTA displays pathological vessels in different retina



layers directly. It is still an ongoing challenge to tell active stage from remission.

Top: Interrelationships among OCT and OCTA raw volume, B-scans, and OCTA projection. OCT B-Scan layer segmentation influences OCTA projection generation.

Contribution

- We experimentally verified that the OCTA projections, which ophthalmologists usually use for diagnosis, are easily affected by layer segmentation errors. Those errors degrade the classification performance.
- We propose to use 3D raw OCTA volume to avoid the impacts of those errors. To achieve this, we modify a pretrained 2D network to perform volume classification. We also adopt an additional projection supervision to facilitate training of shallow feature extractor.
- Experimental results show that the proposed classifier can achieve the accuracy of more than 80%, regardless of the presence of layer segmentation errors. These results prove the effectiveness of our methods and suggest that OCTA is a promising modality to distinguish various stages of AMD disease.

Methods

(a) 2D OCTA Projection Input

Classifier structure: One additional convolution layer to convert input channels; Adjusted the

Layer Segmentation Error

Error Population

sample type	Active	Remission	Dry	Normal	Total
# w/ seg. error	138	91	57	2	288
# w/o seg. error	52	39	90	61	242
error percentage	72.6%	70%	38.8%	3.2%	54.3%

noise

≻Visual Inspection

incorrect vascular network



missing vessels

➤Classification Accuracy

Train on	Test on	Accuracy
Clean set	Clean set	69.64%
Clean set	Mixed set	53.57%
Mixed set	Clean set	64.29%
Mixed set	Mixed set	57.14%

- R1,2: Hard to generalize from clean to mixed
- R1,2,4: Possible to learn the joint distribution

are hard to learn.

R3,4 Samples with errors

output of the last FC to match the number of categories.

Warmup strategy: first freeze all the blue layers and train only the red ones for 600 epochs; Then finetune all the layers together for another 900 epochs with a smaller learning rate.



Experimental Results

Data Preparation:

The dataset consists of 697 raw OCTA volumes with projections: active 182, remission 187, dry 188 and normal 140.

Confusion Matrices:



Error-free subset only has samples with no layer segmentation errors; Error-prone subset contains numerous samples with errors.

Results:

2D Input	Setting		Error-free		Error-prone		2D Input	Setting		Error-free		Error-prone	
	MM	PT	Accuracy	AUC	Accuracy	AUC	5D Input	PT	PS	Accuracy	AUC	Accuracy	AUC
Thakoor	X	×	55.36	0.8159	57	0.8176	Effic.Net 3D	X	X	75	0.9489	69	0.8841
et. al. [30]	\checkmark	X	62.5	0.8512	66	0.8428	Mod Not24 [7]		X	72.01	0.0220	72	
ours(2D)	×	X	73.21	0.8565	62	0.8065		V		/3.21	0.9238	15	0.9009
	×	\checkmark	80.36	0.9264	72	0.8697	ours(3D)		×	82.14	0.9524	74	0.9055
Human	-	_	58.92	-	60	_			\checkmark	83.93	0.9298	80	0.912

* MM: Multimodal information (including OCT B-scan, OCT and OCTA projections), PT: Pretraining. PS: Projection Supervision. **Discussion**: **Confusion Matrices**:

- [30] vs Ours(2D): EfficientNet backbone and Imagenet pretrained model helps.
- Human vs Ours(2D): Proving the potential of OCTA as a diagnostic modality for AMD.
- Ours(2D) vs Ours(3D), Error-free vs Error-prone: Directly analyzing 3D raw data benefits
- 3D Conv vs Ours(3D): Well-designed 2D CNN is better than 3D when training data is limited.
- Ours(3D): Our proposed projection supervision is helpful.

Layer segmentation error degrades accuracy on Dry;

Human struggled to

distinguish remission

from active;

Ours-3D performs well and resist layer segmentation error better.